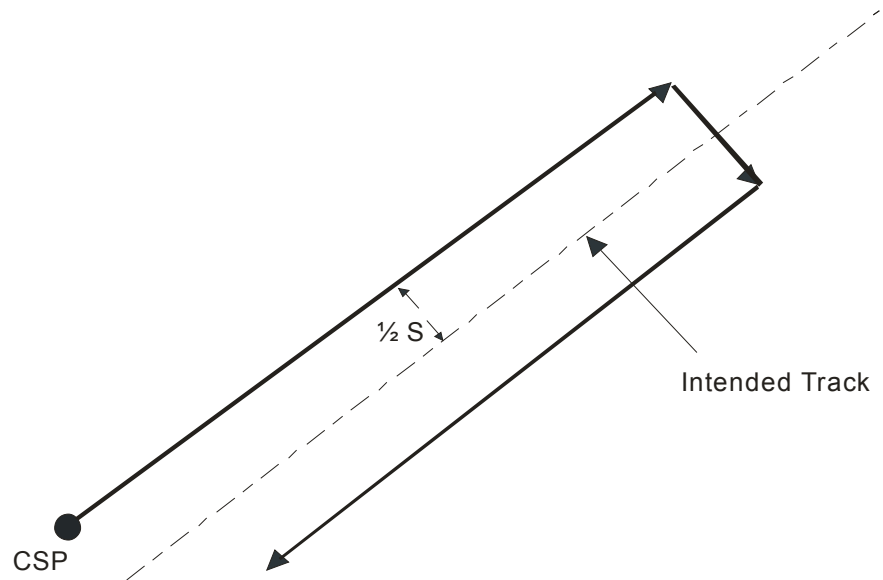


TRACK CRAWL – RETURN TO CSP



CSP- **C**ommence **S**earch **P**oint

$\frac{1}{2} S$ – traverse $\frac{1}{2}$ of the spacing from the intended track

Intended track – line from Last Known Point (LKP) to intended destination.

* With this pattern, searchers return to starting point.

